

2.9 (b) Reduction of the augmented coefficient matrix leads to

$$\begin{bmatrix} 4 & -8 & 12 \\ 3 & -6 & 9 \\ -2 & 4 & -6 \end{bmatrix} \rightarrow \begin{bmatrix} 1^* & -2 & 3 \\ 3 & -6 & 9 \\ -2 & 4 & -6 \end{bmatrix} \rightarrow \begin{bmatrix} 1^* & -2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

The basic variable is x_1 and the free variable is x_2 . The reduced form of the system is

$$\begin{cases} x_1 = 2t + 3 \\ x_2 = t, \end{cases}$$

where $t \in \mathbb{R}$.

2.14 Reduction of the augmented coefficient matrix leads to

$$\begin{bmatrix} 1^* & 2 & -3 & 4 \\ 3 & -1 & 5 & 2 \\ 4 & 1 & a^2 - 14 & a + 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & -7 & 14 & -10 \\ 0 & -7 & a^2 - 2 & a - 14 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & -7 & 14 & -10 \\ 0 & 0 & a^2 - 16 & a - 4 \end{bmatrix} \\ \rightarrow \begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & 1 & -2 & \frac{10}{7} \\ 0 & 0 & a^2 - 16 & a - 4 \end{bmatrix}.$$

We distinguish three cases:

If $a = 4$, then further reduction leads to

$$\rightarrow \begin{bmatrix} 1^* & 2 & -3 & 4 \\ 0 & 1^* & -2 & \frac{10}{7} \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & \frac{8}{7} \\ 0 & 1 & -2 & \frac{10}{7} \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

In this case we have an infinite number of solutions.

If $a = -4$, then further reduction leads to

$$\begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & 1 & -2 & \frac{10}{7} \\ 0 & 0 & 0 & -8 \end{bmatrix}.$$

In this case the system is inconsistent: there are no solutions.

If $a \neq 4$ and $a \neq -4$, then further reduction leads to

$$\begin{bmatrix} 1 & 0 & 1 & \frac{8}{7} \\ 0 & 1 & -2 & \frac{10}{7} \\ 0 & 0 & 1^* & \frac{1}{a+4} \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & \frac{8}{7} - \frac{1}{a+4} \\ 0 & 1 & 0 & \frac{\frac{10}{7} + 2}{a+4} \\ 0 & 0 & 1 & \frac{1}{a+4} \end{bmatrix}.$$

In this case the system has a unique solution.

2.15 (b) Since (s_1, t_1) is a solution of the system (1),

$$\begin{cases} a s_1 + b t_1 = k \\ a s_1 + d t_1 = l \end{cases}$$

and since (s_0, t_0) is a solution of the system (2)

$$\begin{cases} a s_0 + b t_0 = 0 \\ c s_0 + d t_0 = 0. \end{cases}$$

So

$$a(s_1 + s_0) + b(t_1 + t_0) = as_1 + as_0 + bt_1 + bt_0 = as_1 + bt_1 + as_0 + bt_0 = k + 0 = k.$$

Similarly,

$$c(s_1 + s_0) + d(t_1 + t_0) = \dots = l + 0 = l.$$

Hence $(s_1 + s_0, t_1 + t_0)$ is a solution of the system (1).

2.18 We distinguish two cases.

If $c = 0$, then the augmented coefficient matrix is

$$\begin{bmatrix} 1 & 0 & 2 & 2 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & d \end{bmatrix}.$$

In view of the second row of this matrix, the system is inconsistent for any value of d .

If $c \neq 0$, reduction of the augmented coefficient matrix leads to

$$\begin{bmatrix} 1 & 0 & 2 & 2 \\ 0 & c & c & 1 \\ 0 & 0 & cd & c+d \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 & 2 \\ 0 & 1 & 1 & c^{-1} \\ 0 & 0 & cd & c+d \end{bmatrix}.$$

If $d = 0$, according to the third row of this matrix, the system is inconsistent for any value of $c \neq 0$.

If $d \neq 0$, further reduction of the matrix leads to

$$\begin{bmatrix} 1 & 0 & 2 & 2 \\ 0 & 1 & 1 & c^{-1} \\ 0 & 0 & 1 & \frac{c+d}{cd} \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 2 - 2\frac{c+d}{cd} \\ 0 & 1 & 0 & c^{-1} - \frac{c+d}{cd} \\ 0 & 0 & 1 & \frac{c+d}{cd} \end{bmatrix}.$$

Hence, the system has a unique solution if $c \neq 0$ and $d \neq 0$.

As we observed before, the system is inconsistent if (1) $c = 0$ or (2) $d = 0$ and $c \neq 0$.

2.19 (a) Note that \underline{x} is in the intersection of the three planes if and only if

$$\begin{cases} \underline{x} \cdot \underline{n}_1 = 2 \\ \underline{x} \cdot \underline{n}_2 = 0 \\ \underline{x} \cdot \underline{n}_3 = q \end{cases} \iff \begin{bmatrix} 1 & 0 & 4 \\ 0 & 2 & 4 \\ 1 & p & p^2q \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ q \end{bmatrix}.$$

So we should in fact determine those values of p and q such that the foregoing system of linear equations has an infinite number of solutions.

In order to answer this question, we reduce the augmented coefficient matrix of the system

$$\begin{bmatrix} 1 & 0 & 4 & 2 \\ 0 & 2 & 4 & 0 \\ 1 & p & p^2q & q \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 4 & 2 \\ 0 & 1 & 2 & 0 \\ 0 & p & p^2q - 4 & q - 2 \end{bmatrix}.$$

If $p = 0$, the system has a unique solution. If $p \neq 0$, we further reduce the matrix to

$$\begin{bmatrix} 1 & 0 & 4 & 2 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & p^2q - 2p - 4 & q - 2 \end{bmatrix}.$$

The system has an infinite number of solutions if (and only if) $p^2q - 2p - 4 = 0$ and $q - 2 = 0$. So $q = 2$ and $p^2 - p - 2 = 0$. Hence, $p = -1$ or $p = 2$.

(b) For the values of p and q we found in part (a), the reduced matrix is

$$\begin{bmatrix} 1 & 0 & 4 & 2 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Hence,

$$\begin{cases} x = 2 - 4z \\ y = -2z \end{cases}$$

is the reduced form of the system and each solution is of the form

$$\begin{bmatrix} 2 - 4z \\ -2z \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} + z \begin{bmatrix} -4 \\ -2 \\ 1 \end{bmatrix},$$

where $z \in \mathbb{R}$. So the intersection of the three planes is a line with vector representation

$$\underline{v} = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -4 \\ -2 \\ 1 \end{bmatrix}.$$

(c) In fact we should determine those values of p such that the foregoing system of linear equations has no solutions.

In order to answer this question, we reduce the augmented coefficient matrix of the system

$$\begin{bmatrix} 1 & 0 & 4 & 2 \\ 0 & 2 & 4 & 0 \\ 1 & p & p^2 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 4 & 2 \\ 0 & 1 & 2 & 0 \\ 0 & p & p^2 - 4 & -1 \end{bmatrix}.$$

Obviously, if $p = 0$, the system has a unique solution.

If $p \neq 0$, further reduction leads to

$$\begin{bmatrix} 1 & 0 & 4 & 2 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & p^2 - 2p - 4 & -1 \end{bmatrix}.$$

The system has no solutions if

$$p^2 - 2p - 4 = 0 \iff p = \frac{2 \pm \sqrt{4 + 16}}{2} = 1 \pm \sqrt{5}.$$

(d) If \underline{v} is a point contained in the three planes with $v_1 = 1$, then v_2 and v_3 satisfy

$$\begin{cases} 1 + 4v_3 = 2 \\ 2v_2 + 4v_3 = 0 \\ 1 + pv_2 + p^2v_3 = 1. \end{cases}$$

According to the first equation, $v_3 = \frac{1}{4}$. In combination with the second equation this leads to $2v_2 + 1 = 0 \implies v_2 = -\frac{1}{2}$. Hence,

$$1 + pv_2 + p^2v_3 = 1 \implies 1 - \frac{1}{2}p + \frac{1}{4}p^2 = 1 \implies p^2 - 2p = 0 \implies p = 0 \text{ or } p = 2.$$