5.6 The mapping can be presented in the following way:



(a) By means of the foregoing figure one finds that

$$T\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}-x\\y\end{bmatrix}.$$

(b) Let  $\underline{u}, \underline{v} \in \mathbb{R}^2$  and  $c \in \mathbb{R}$ . Then

$$T(\underline{u} + \underline{v}) = T\left( \begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \end{bmatrix} \right) = \begin{bmatrix} -u_1 - v_1 \\ u_2 + v_2 \end{bmatrix} = \begin{bmatrix} -u_1 \\ u_2 \end{bmatrix} + \begin{bmatrix} -v_1 \\ v_2 \end{bmatrix} = T(\underline{u}) + T(\underline{v}),$$

and

$$T(c\underline{u}) = T\left(\begin{bmatrix} cu_1\\ cu_2 \end{bmatrix}\right) = \begin{bmatrix} -cu_1\\ cu_2 \end{bmatrix} = c\begin{bmatrix} -u_1\\ u_2 \end{bmatrix} = cT(\underline{u})$$

According to the definition T is a linear mapping.

5.8 We consider the mapping  $T: \mathbb{R}^n \to \mathbb{R}^m$  defined by

 $T(\underline{x}) = A\underline{x} + \underline{b},$ 

where A is an  $m \times n$  matrix and  $\underline{b} \in \mathbb{R}^m$ .

We will prove that T is linear if and only if  $\underline{b} = \underline{0}$ .

(a) Assume that T is linear. Then on the one hand

$$\Gamma(0 \cdot \underline{u}) = 0 \cdot T(\underline{u}) = \underline{0}$$

and on the other hand

$$T(0 \cdot \underline{u}) = A\underline{0} + \underline{b} = \underline{b}.$$

So  $\underline{b} = \underline{0}$ .

(b) Assume that  $\underline{b} = \underline{0}$ . Then T is the left multiplication by a matrix. So T is linear.

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5.9 (a) As observed in Chapter 3, a vector  $\underline{x} \in \mathbb{R}^n$  can be written as a linear combination of the unit vectors:

$$\underline{x} = x_1 \, \underline{e}_1 + x_2 \, \underline{e}_2 + \dots + x_n \, \underline{e}_n.$$

Since the mapping T is linear, the observation preceding this exercise implies that for all  $\underline{x} \in \mathbb{R}^n$ 

$$T(\underline{x}) = T(x_1 \underline{e}_1 + x_2 \underline{e}_2 + \dots + x_n \underline{e}_n) = x_1 T(\underline{e}_1) + x_2 T(\underline{e}_2) + \dots + x_n T(\underline{e}_n)$$

$$= x_1 \underline{e}_1 + x_2 \underline{e}_2 + \dots + x_n \underline{e}_n = \underline{x}.$$

So T is the identical mapping.

(b) The mapping T is the left-multiplication by the matrix  $\begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}.$ 

## 5.12 (a) We give a prove based on the definition (of a linear map).

Let  $\underline{u}, \underline{v} \in \mathbb{R}^n$  and  $c \in \mathbb{R}$ . Then

$$(T_1 + T_2)(\underline{u} + \underline{v}) = T_1(\underline{u} + \underline{v}) + T_2(\underline{u} + \underline{v}) \quad (\text{according to the definition of } T_1 + T_2)$$
$$= T_1(\underline{u}) + T_1(\underline{v}) + T_2(\underline{u}) + T_2(\underline{v}) \quad (\text{because } T_1 \text{ and } T_2 \text{ are linear})$$
$$= T_1(\underline{u}) + T_2(\underline{u}) + T_1(\underline{v}) + T_2(\underline{v})$$
$$= (T_1 + T_2)(\underline{u}) + (T_1 + T_2)(\underline{v}),$$

and

$$(T_1+T_2)(c\underline{u}) = T_1(c\underline{u}) + T_2(c\underline{u}) = cT_1(\underline{u}) + cT_2(\underline{u}) = c[T_1(\underline{u}) + T_2(\underline{u})] = c(T_1+T_2)(\underline{u}).$$

Next we will give a proof by using the standard matrix.

Let  $A_1$  be the standard matrix corresponding to  $T_1$  and let  $A_2$  be the standard matrix corresponding to  $T_2$ . Then  $T_1(\underline{u}) = A_1\underline{u}$  and  $T_2(\underline{u}) = A_2\underline{u}$  for all  $\underline{u} \in \mathbb{R}^n$ . This however means that for every  $\underline{u} \in \mathbb{R}^n$ 

$$(T_1 + T_2)(\underline{u}) = T_1(\underline{u}) + T_2(\underline{u}) = A_1\underline{u} + A_2\underline{u} = (A_1 + A_2)\underline{u}.$$

This proves that the mapping  $T_1 + T_2$  is the left multiplication by the matrix  $A_1 + A_2$ . Hence the mapping  $T_1 + T_2$  is linear.

(b) For a vector  $\underline{v} \in \text{Ker}(T_1) \cap \text{Ker}(T_2)$  it holds that  $T_1(\underline{v}) = T_2(\underline{v}) = \underline{0}$ . By consequence,

$$(T_1 + T_2)(\underline{v}) = T_1(\underline{v}) + T_2(\underline{v}) = \underline{0} + \underline{0} = \underline{0},$$

in other words:  $\underline{v} \in \text{Ker}(T_1 + T_2)$ .

(c) Consider the mappings  $T_1: \mathbb{R}^2 \to \mathbb{R}^2$  and  $T_2: \mathbb{R}^2 \to \mathbb{R}^2$  defined by

$$T_1(\underline{x}) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \underline{x} \quad \text{and} \quad T_2(\underline{x}) = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \underline{x} \quad (\underline{x} \in \mathbb{R}^2).$$

Then  $\operatorname{Ker}(T_1) = \operatorname{Ker}(T_2) = \{\underline{0}\}$ . However, for every  $\underline{x} \in \mathbb{R}^2$  it holds that

$$(T_1 + T_2)\underline{x} = \begin{bmatrix} 0 & 0\\ 0 & 0 \end{bmatrix} \underline{x} = \underline{0}$$

which implies that  $\operatorname{Ker}(T_1 + T_2) = \mathbb{R}^2$ .

5.13 (a) Let  $\underline{u}, \underline{v} \in \mathbb{R}^2$ . Then

$$T(\underline{u}) = T(\underline{v}) \Longleftrightarrow \begin{bmatrix} u_1 \\ u_2 \\ u_1 + u_2 \end{bmatrix} = \begin{bmatrix} v_1 \\ v_2 \\ v_1 + v_2 \end{bmatrix} \Longleftrightarrow \begin{cases} u_1 = v_1 \\ u_2 = v_2 \end{cases} \Longleftrightarrow \underline{u} = \underline{v}.$$

Hence, the mapping T is one-to-one.

(b) Since

$$T(\underline{0}) = T\left( \begin{bmatrix} 1\\1 \end{bmatrix} \right),$$

the mapping T is not one-to-one.

5.15 (a) Let  $x, y \in \mathbb{R}$ . Then

$$T\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}1 & 0\\1 & 0\end{bmatrix}\begin{bmatrix}x\\y\end{bmatrix}.$$

Hence, the mapping T is the left-multiplication by the matrix

$$A = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}.$$

So the mapping T is linear.

(b) Note that

$$\operatorname{Im}(T) = \operatorname{Col}(A) = \operatorname{span}\left\{ \begin{bmatrix} 1\\1 \end{bmatrix}, \begin{bmatrix} 0\\0 \end{bmatrix} \right\} = \operatorname{span}\left\{ \begin{bmatrix} 1\\1 \end{bmatrix} \right\}.$$

This set corresponds with the line y = x in the x, y-plane.

Note that Ker(T) = Null(A). Since

$$A\underline{x} = \underline{0} \iff x_1 = 0 \iff \underline{x} = c \underline{e}_2$$
 for some  $c \in \mathbb{R}$ ,

 $\operatorname{Ker}(T) = \operatorname{Null}(A) = \{ c \underline{e}_2 | c \in \mathbb{R} \} = \operatorname{span}\{ \underline{e}_2 \}.$ 

This set corresponds with the line x = 0 in the x, y-plane.